# Visual Encoders

Vision+Language Seminar (Fall 2024)

(1) Contrastive pre-training



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(1) Contrastive pre-training



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(1) Contrastive pre-training



 $I:B\times H\times W\times 3$  $T: B \times S$  $e_I = \text{ImageEncoder}(I) \# (B, D)$  $e_T$  = TextEncoder(T) # (B, D)  $e_I = L2\_norm(e_I)$  $e_T = L2_{\text{norm}}(I_T)$  $cosine\_sim = e_Ie_T^T \exp(\tau) \# (B, B)$  $logits1 = log_softmax(cosine_sim, dim = 0)$  $logits2 = log_softmax(cosine_sim, dim = 1)$  $loss1 = (logits1 * Identity(B)).$  sum()  $loss2 = (logits2 * Identity(B)).$  sum()  $loss = (loss1 + loss2)/2$ 

#### (2) Create dataset classifier from label text





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certain search volume. Finally all WordNet (Miller, 1995) synsets not already in the query list are added.

We approximately class balance the results by including up to 20,000 (image, text) pairs per query. The resulting

## Can we use CLIP to resolve spatial relations?



"a yellow cube is in front of a blue cube" **CLIP** "a yellow cube is behind a blue cube"



# Can we use CLIP to resolve spatial relations?



### **Control task**

"a blue cube and a yellow cube"

"a blue cube and a yellow sphere"



# Can we use CLIP to resolve spatial relations?

#### **Spatial** Non-spatial







Comparison with Same Training Data



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3 observations:

- 1. Sigmoid vs. Softmax difference is mainly visible at small BS
- 2. Sigmoid worse than Softmax at largest BS
- 3. Both methods worse at largest BS than medium BS

Contrastive training typically utilizes data parallelism. Computing the loss when data is split across  $D$  devices necessitates gathering all embeddings [59] with expensive all-gathers and, more importantly, the materialization of a memory-intensive  $|\mathcal{B}| \times |\mathcal{B}|$  matrix of pairwise similarities.

days. We also present from-scratch results in the bottom rows of Table 1: with 32 TPUv4 chips for only two days, SigLIP achieves 72.1% 0-shot accuracy. This presents a significant training cost reduction e.g. compared to CLIP (approx. 2500 TPUv3-days for  $72.6\%$ ) reported in [30].



Cross Device  $\Sigma$ 

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- Random: Randomly choose negative pairs to mask.
- Hard: Keep hardest negative pairs (highest loss).
- Easy: Keep easiest negatives pairs (lowest loss).
- Hard + matching total pairs seen: Masking examples while training for a fixed number of steps does decrease the total number of *pairs* seen during training. Hence in the *matched pairs* setting, we increase the number of training steps by the masking ratio in order to keep the number of pairs seen constant.

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image



scale alt-text data and annotated images by treating all labels simply as texts. We use the JFT-3B dataset  $[21]$  with label names as the paired texts, and the ALIGN dataset  $[13]$  with noisy alt-texts.





(b) Training objectives ablation.

# Discussion Questions (about SigLIP)

- Latest MLLMs usually use SigLIP instead of CLIP as the default vision encoder because people find SigLIP is consistently better on different MLLM benchmarks. However, we are still not clear is this advantage due to the loss design or the data?
- Prior work found that increasing batch size improves the training with contrastive loss objective. Why is the peak performance at 32k batch size? What's the intuition behind this result? Is it due to large class imbalance and that negative examples grow quadratically (N^2-N) compared to linear growth of positive examples (N)? How can we improve large-batch size performance (1M)?
- The results in Figure 7, which show that the proposed method leads to models which have improved noise robustness, suggests that the sigmoid loss is having some kind of regularization effect beyond the softmax loss. What could be the mechanism/explanation behind this?